

RLC2HD

Miniature Incremental Magnetic Encoder Module

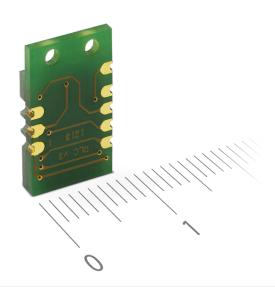
MINIATURE DESIGN

RLC2HD is a PCB-level incremental encoder system consisting of a PCB sensor and a magnetic scale or ring. It is designed for embedded motion control applications as a position control loop element in applications with limited space.

HIGH OPERATING SPEED

The state-of-the-art position detection guarantees a highly repeatable position measurement under wide installation tolerances and temperature ranges. The position information is output in incremental quadrature format with the periodic reference mark option (each pole).

EASY INSTALLATION WITH SOLDERING



Features and benefits

- ▶ Miniature design: 8 x 2.1 x 12.5 mm
- ► Incremental quadrature A, B, Z (TTL)
- ▶ Periodic-bidirectional reference mark
- ► High-speed operation

- Suitable for use with linear scale, radial and axial rings
- ▶ SMT solder to a customer PCB board
- RoHS compliant











General information

The RLC2HD is a miniature rotary and linear encoder that can be used in space-constrained applications. The readhead provides a single-ended incremental signal and is ideally soldered to the customer's electronics.

Choose your RLC2HD system

The robust RLC2HD readhead is compatible with the RLS incremental scale MS05 as well as the RLS axial and radial rings. You can select the length of the MS05 scale up to 50 m. There is also a wide range of axial and radial incremental rings available. To ensure safety and reliability, the scale MS05 and the radial rings can be optionally covered with a protective stainless steel foil.

RLC2HD + magnetic scale



More about the MS magnetic scales can be found in the MSD01 at **RLS media center**.

RLC2HD + radial magnetic ring



More about the radial rings can be found in the MR02D02 at **RLS media center**.

RLC2HD + axial magnetic ring



More about the axial rings can be found in the MR01D01 at **RLS media center**.



Storage and handling

All data given below refer to the readhead only. Complete systems with magnetic scale or ring may have other limitations. For more information, see the MSD01, MR02D02 or MR01D01 data sheet at **RLS Media center**.

Storage temperature



-40 °C to +85 °C

-40 °C to +60 °C (Tape and reel packaging)

Operating temperature

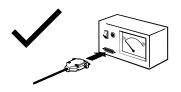


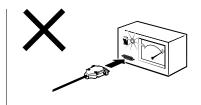
-30 °C to +85 °C

Humidity



Up to 70 % non-condensing Up to 10 % (before soldering)







The encoder is a mechanically sensitive component. Handle it by its edges, touch it lightly, minimize pressure and eliminate bending while maintaining a secure grip to prevent falls. Maximize cleanliness. When it's not in use, place it in an ESD protective packaging (box or tray).



Readhead is ESD sensitive - handle with care.

Do not touch electronic circuit, wires or sensor area without proper ESD protection or outside of ESD controlled environment.

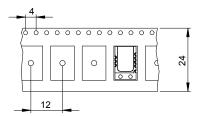
Packaging

Up to 20 pcs packaged individually in an antistatic box. 20+ units packaged in trays (max. 120 pcs per tray, 21 trays per box).

Tape and reel packaging (special option 07)

W24/P12/T0.3 in 13" reel

The minimum order quantity for reel packaging is 2000 pcs.

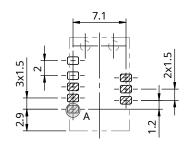


Dimensions and installation drawings

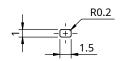
Dimensions and tolerances are in mm. Dimensions without tolerance values are in accordance with ISO 2768-m.

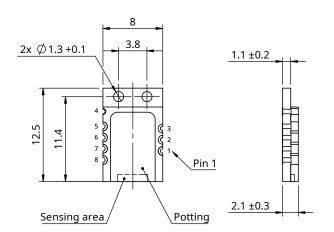


PCB footprint



Detail A: Valid for all 8 pads



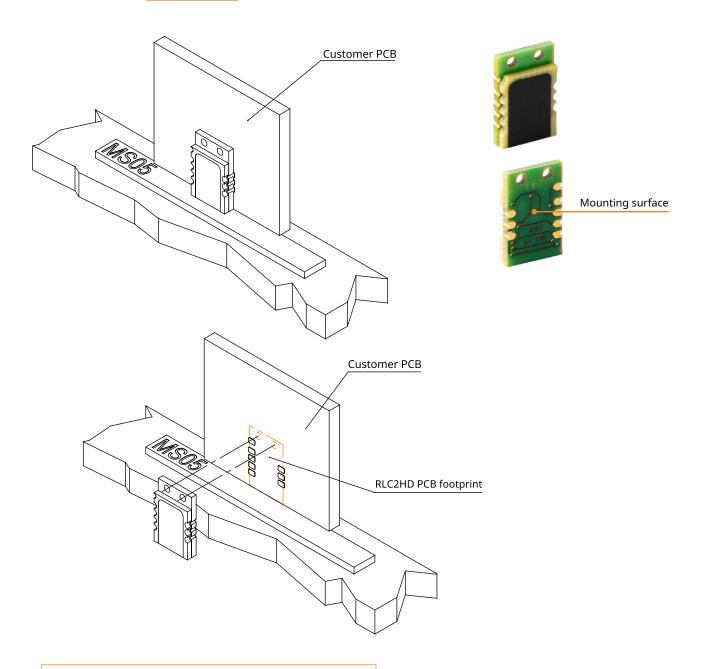


3D model available for download at **RLS Media center.**



Installation instructions

When mounting the RLB, make sure that only the mounting surfaces of the PCB assembly are in contact with the mounting bracket. All other parts of the PCB assembly should maintain a minimum distance of 0.1 mm from other metal objects. All permissible distance and angle tolerances must be strictly complied according to the mounting instructions found at MSD01, MR01D01 or MR02D02 data sheet at **RLS Media center**.



Images are for illustration purposes only. Valid for all versions.

To avoid mechanical damage to the PCB assembly, do not use countersunk fasteners.

- It is important that the space between the readhead and the magnetic scale is maintained over the entire measuring range.
- The magnetic encoder system must be used in accordance with the specified degree of protection. The following factors must be taken into account: IP protection class, operating temperature, external magnetic field, humidity level, mechanical load and EMC compatibility.
- The magnetic encoder system is sensitive to the external magnetic fields. The magnitude of the influence on the magnetic encoder system depends on the magnitude and direction of the external magnetic field. In particular, the rapidly changing stray magnetic fields affect the system and can alter its function. Magnetic field strength within 1 mT reduces the accuracy of the system. Field strengths greater than 1 mT will cause the system to malfunction and as a result the readhead will report an incorrect position. Magnetic field strengths greater than 25 mT will cause irreversible damage to the magnetic scale or ring and will have to be replaced.

Technical specifications

Pole length		2 mm			
Maximum measur	ing length	50 m			
System accuracy	Linear application	±10 μm/m / ±20 μm/m / ±40 μm/m			
	MS05 magnetic scale	Different accuracy grades of MS05 magnetic scale available. Refer to MSD01			
		available at RLS Media center.			
	Rotary application	Axial: Refer to MR01D01 available at RLS media center.			
		Radial: Refer to MR02D02 available at RLS media center.			
Hysteresis		< 3 µm (at 0.3 mm ride height)			
Repeatability (unio	directional)	< 1 µm			
Reference mark		Periodic			
Set-up time		< 50 ms (after power supply voltage is set in operating range)			
Resolution		Max. 13 bit (~0.244 μ m) For details refer to the Table of available resolutions .			
Maximum speed	Linear application	Refer to speed calculator available at RLS website .			
	Rotary application	Axial: Refer to speed calculator available at RLS website.			
		Radial: Refer to speed calculator available at RLS website.			
Electrical data	a				
Power supply		5 V ±0.25 V – voltage on readhead			
Current consumption		< 20 mA			
Reverse polarity protection		Without reverse polarity protection			
Mechanical d	ata				
Mass		1.25 g			



Environmental data

Temperature	Operating	−30 °C to +85 °C			
	Storage	–40 °C to +85 °C –40 °C to +60 °C (Tape and reel packaging)			
Vibrations (55 Hz to 2000 Hz)		300 m/s² (IEC 60068-2-6)			
Shocks (6 ms)		300 m/s² (IEC 60068-2-27)			
Moisture level		MSL6 (IPC/JEDEC-J-STD-020)			
Baking procedure		48 h/125 °C or according to IPC/JEDEC-J_STD_033			
Humidity		70 % non-condensing			
		10 % (before soldering)			
External magnetic field during operation		< 1 mT			
ESD immunity		HBM, Class 2 ±2kv			
ESD immunity					

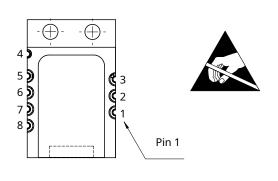
Reflow data

Moisture level	MSL6
Maximum reflow temperature	245 °C

Solder in 24h after bag is opened.

Electrical connections

Pin	Signal
1	Vdd
2	Vdd
3	GND
4	NC
5	NC
6	Z
7	В
8	Α



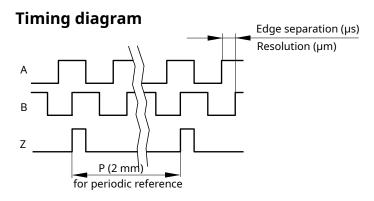
Output type

Incremental, no line driver

RLC2HD

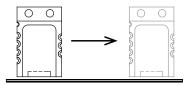
Specifications

Output signals	Digital – TTL-level (A, B, Z)
Saturation voltage hi (I = −4 mA)	V _{dd} – 0.4 V
Saturation voltage Io (I = 4 mA)	0.4 V
Rise and fall time ($c_c = 50 \text{ pF}$)	60 ns



Positive direction

Digital output signals – A leads B



For more information, see the MSD01, MR02D02 or MR01D01 data sheet at **RLS Media center**.



Part numbering

		RLC	2	HD	Α	13B	Α	00	С	0
Pole length										
2 - 2 mm										
.										
Dutput type H D - Incremental, no l	ine driver									
,										
Option A - Standard										
A - Standard										
Interpolation factor (Resolutions)*		Ma	x Speed C	alculato	rs				
13B - 8192 (~0.244 μm)		μm)		- 100 (~20	•					
12B - 4096 (~0.488 µm) 11B - 2048 (~0.976 µm)				- 80 (~25 μ - 64 (~31.2						
2D0 - 2000 (~1 μm)	D32 - 320 (~6.25 μ		D04	- 40 (~50 µ	ım)					
1D6 - 1600 (~1.25 μm) 10B - 1024 (~1.953 μm)	08B - 256 (~7.812 D20 - 200 (~10 μm		05B - 32 (~62.5 μm) 04B - 16 (~125 μm)							
1D0 - 1000 (~2 μm)	D16 - 160 (~12.5 μ			- 8 (~250 µ						
D80 - 800 (~2.5 μm)	07B - 128 (~15.625	5 μm)								
* For exact values see tabl	e of Available resolution	<u>s</u> .								
Minimum edge separ	ation			<u>Max</u>	Speed Ca	alculators				
K - 0.07 μs (15 MHz)	E - 4 μs (0.25 MHz)									
A - 0.12 μs (8 MHz) B - 0.5 μs (2 MHz)	F - 5 μs (0.2 MHz) G - 10 μs (0.1 MHz) H - 20 μs (0.05 MHz)					1				
C - 1 µs (1 MHz)						support the even if the				
D - 2 μs (0.5 MHz)			_	· ·		mum spee				
Connector										
00 - No connector, thi	rough-hole									
Reference mark										
	e mark as per scale pitch	(every 2 r	mm)							
Reference periods o	orrespond to pole length of r	_		netic scale	or ring mu	st be ordere	ed with			
no reference mark.										

Special requirements

- **00** No special requirements (standard)
- 07 Tape and reel packaging (The minimum order quantity for reel packaging is 2000 pcs. For large quantities see page 3)

Not all part number combinations are valid. Please refer to the table of available combinations on the next page for available options.

Table of available combinations

Series	Pole length	Output type	Option	Interpolation factor	Minimum edge separation	Connector	Reference mark	Special requirements
	RLC 2 HD A) А	xxx*	K/A/B/C/D/E/ F/G/H	00	C	00 / 07	
RLC			04B	A/B/C/D/E/F /G/H				
		03B	B/C/D/E/F/ G/H					

^{*}Please check the table below for available interpolation factors.

For the part numbering of the MS incremental magnetic scale or the MR radial and axial incremental magnetic ring, refer to the MSD01, MR02D02 or MR01D01 data sheet at **RLS Media Center**.

Available resolutions

Table of available resolutions

Part number	Pole length [mm]	Interpolation factor	Resolution [μm]
13B	_	213	0.244140625
12B		212	0.48828125
11B		211	0.9765625
2D0		2000	1
1D6		1600	1.25
10B		210	1.953125
1D0		1000	2
D80		800	2.5
09B		29	3.90625
D50		500	4
D40		400	5
D32	2	320	6.25
08B		28	7.8125
D20		200	10
D16		160	12.5
07B		27	15.625
D10		100	20
D08		80	25
06B	_	2 ⁶	31.25
D04	_	40	50
05B		2 ⁵	62.5
04B	_	24	125
03B		23	250

Resolutions calculation

 $Resolution \ [\mu m] \ = \frac{Pole \ length \ [\mu m]}{Interpolation \ factor} = \frac{2000}{Interpolation \ factor}$

For ring applications:

CPR - Counts per revolution (resolution)

Resolution [CPR] = Pole number* x Interpolation factor

PPR - Pulses per revolution

Resolution [PPR] =
$$\frac{\text{Resolution [CPR]}}{4}$$

*See pole numbers in the MR01D01 or MR02D02 data sheet at **RLS Media center.**



Accessories





Line driver board for incremental encoders LDB01



USB encoder interface **E201-9Q**

 ${\sf E201-9Q}\ should\ be\ used\ with\ adapter\ to\ transfer\ from\ single\ ended\ to\ differential.$



Head office

RLS Merilna tehnika d. o. o.

Poslovna cona Žeje pri Komendi Pod vrbami 2 SI-1218 Komenda Slovenia **T** +386 1 5272100 **E** mail@rls.si

www.rls.si

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Date	Issue	Page	Description
19. 12. 2022	4	General	New design, data amended
7 4 2022	5	6	Installation instructions data added
7. 4. 2023		8	Output type specifications amended
15. 9. 2023	6	9	Menu (button) Max Speed Calculators added
13. 10. 2023	7	6	Set-up time amended
45 7 2024	8	3, 9	Minimum order quantity for reel packaging added
15. 7. 2024		11	LDB01 added
4. 9. 2024	9	3, 7	Environmental data amended

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